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IEE CNF	IEE Conference Proceeding	1	. Combining a stable 2-D vision camera and an ultrasonic range detector for 3-D position estimation
IEEE STD	IEEE Standard	IJ '	Nilsson, A.; Holmberg, P.;
			Instrumentation and Measurement, IEEE Transactions on Volume 43, Issue 2, Apr 1994 Page(s):272 - 276
			AbstractPlus   Full Text: PDF(432 KB) IEEE JNL
		_ · 2	. Multiple-sensor integration for rapid and high-precision coordinate metrology
		□ ²	Tzung-Sz Shen; Jianbing Huang; Chia-Hsiang Menq;
			Mechatronics, IEEE/ASME Transactions on
			Volume 5, Issue 2, June 2000 Page(s):110 - 121
			AbstractPlus   References   Full Text: PDF(624 KB)   IEEE JNL
•		□ ³	Recognition of position and orientation of jumbled parts using cross slit light 3-D vision sensor Ozeki, O.; Nakano, T.; Higuchi, K.; Yamamoto, S.; Industrial Applications of Machine Intelligence and Vision, 1989., International Workshop on 10-12 April 1989 Page(s):40 - 45
			AbstractPlus   Full Text: PDF(356 KB) IEEE CNF
		□ <b>⁴</b>	<ul> <li>Mobile robot localization using a single image         Krotkov, E.;         Robotics and Automation, 1989. Proceedings., 1989 IEEE International Conference on 14-19 May 1989 Page(s):978 - 983 vol.2     </li> </ul>
			AbstractPlus   Full Text: PDF(500 KB) IEEE CNF
		□ <sup>5</sup>	Shabestari, B.N.; Miller, J.W.V.; Wedding, V.; Systems Engineering, 1991., IEEE International Conference on 1-3 Aug. 1991 Page(s):273 - 275
		,	AbstractPlus   Full Text: PDF(200 KB) IEEE CNF
		_	
		□ 6	Combining a stable 2-D vision camera and an ultrasonic range detector for 3-D position estimation Nilsson, A.; Holmberg, P.; Instrumentation and Measurement Technology Conference, 1993. IMTC/93. Conference Record., IEEE 18-20 May 1993 Page(s):453 - 458
			AbstractPlus   Full Text: PDF(460 KB) IEEE CNF
•		7	Recognition via blob representation and relational voting
			· Necodinion via nico representation and relational Young

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L1	19	("4115761"   "4281312"   "4388610"   "4630307"   "4686636"   "4712248"   "4910608"   "5016173"   "5022091"   "5060280"   "5280530"   "5325444"   "5416899"   "5457754"   "5459636"   "5479529"   "5537662"   "5568384"   "5995639").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2005/04/18 12:16
L2	30750	(elements or marks or parts) near3 (similarity or match\$3 or resemb\$5 or correlat\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/04/18 12:18
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L7	2965	2 same 6	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/04/18 12:21
L8	352	7 same (image\$1 or picture\$1)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/04/18 12:54

L9	458	chang-jon.xp.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/04/18 12:54
L10	25	9 and (character near3 position\$1)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/04/18 12:55
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S1	1	("20020146174").PN.	US-PGPUB; USPAT	OR	OFF	2005/04/02 14:16
S2	1	matsugu-\$.in. and chang-jon.xp.	US-PGPUB; USPAT	OR	OFF	2005/04/02 15:14
S3	1	"4388610".PN.	USPAT; USOCR	OR	OFF	2005/04/02 14:30
S4	4542	second\$3 near2 score\$1	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/04/02 16:22
S5	157	S4 near6 (resembl\$5 or similarit\$3 or match\$3 or coinciden\$2)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/04/02 16:38
S6	61831	second\$3 near4 (resembl\$5 or similarit\$3 or match\$3 or coinciden\$2)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/04/02 15:36
<b>S7</b>	57060	second near4 (resembl\$5 or similarit\$3 or match\$3 or coinciden\$2)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/04/02 16:30

S8	4749	S7 same (image\$1 or picture\$1 or photograph\$1 or template\$1)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/04/02 16:32
S9	131	S7 same ((count\$3 or number\$1 or amount\$1) near3 (pixel\$1 or pel\$1 or (picture adj element\$1)))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/04/02 16:32
S10	1862	two near2 scores	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/04/02 16:22
S11	71	S10 near6 (resembl\$5 or similarit\$3 or match\$3 or coinciden\$2)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/04/02 16:23
S12	8231	second near4 (correlation\$1)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/04/02 16:30
S13	1372	S12 same (image\$1 or picture\$1 or photograph\$1 or template\$1)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/04/02 16:32
S14	54	S13 same ((count\$3 or number\$1 or amount\$1) near3 (pixel\$1 or pel\$1 or (picture adj element\$1)))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/04/02 16:45
S15	25	S4 near6 (correlation\$1)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/04/02 16:40
S16	1428	(382/194,209,217,218).CCLS.	US-PGPUB; USPAT	OR	OFF	2005/04/02 16:41
S17	376	S16 and (S4 or S5 or S7 or S8 or S9 or S12 or S13 or S14)	US-PGPUB; USPAT	OR	OFF	2005/04/02 16:43

S18	376	S16 and (S4 or S7 or S12)	US-PGPUB; USPAT	OR	OFF	2005/04/02 16:44
S19	31	S16 and (S5 or S9 or S14)	US-PGPUB; USPAT	OR	OFF	2005/04/02 16:44
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S21	150	S20 and ((@ad<"20020123") or (@rlad<"20020123"))	US-PGPUB; USPAT	OR	OFF	2005/04/02 16:46